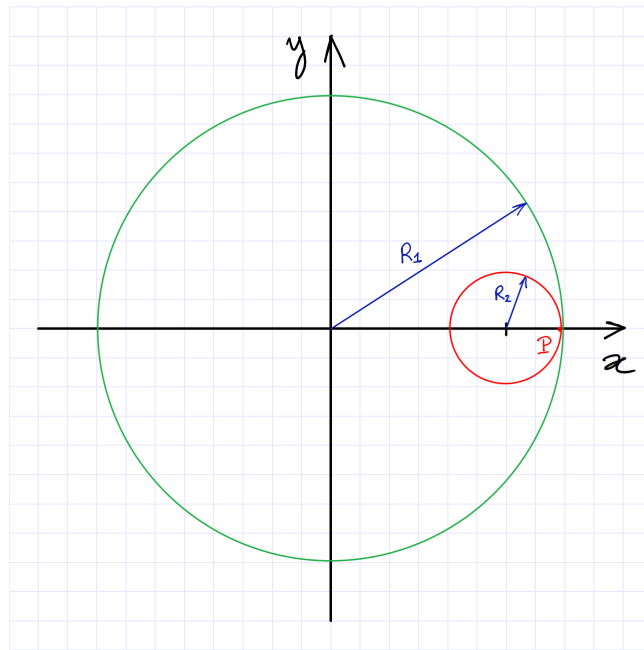


Homework 6

- (I) Given $\vec{A} = 2\hat{x} - 3\hat{y} + 7\hat{z}$ and $\vec{B} = 5\hat{x} + \hat{y} + 2\hat{z}$ with $\hat{x}, \hat{y}, \hat{z}$ an orthonormal basis ($\hat{x} \cdot \hat{x} = \hat{y} \cdot \hat{y} = \hat{z} \cdot \hat{z} = 1$ while $\hat{x} \cdot \hat{y} = \hat{x} \cdot \hat{z} = \hat{y} \cdot \hat{z} = 0$).
- (a) [1 pts.] Find $\vec{A} + \vec{B}$.
 - (b) [1 pts.] Find $\vec{A} - \vec{B}$.
 - (c) [2 pts.] Find $|\vec{A}|$.
 - (d) [2 pts.] Find $\vec{B} \cdot \vec{B}$.
 - (e) [2 pts.] Find $\vec{A} \cdot \vec{B}$.
 - (f) [2 pts.] Find the cosine of the angle between \vec{A} and \vec{B} .
- (II) [10 pts.] Show that if $|\vec{A} - \vec{B}| = |\vec{A} + \vec{B}|$, then \vec{A} and \vec{B} are perpendicular.
- (III) [10 pts.] \hat{A} and \hat{B} are unit vectors making angles θ_A and θ_B with the x -axis. By calculating $\hat{A} \cdot \hat{B}$ express $\cos(\theta_A - \theta_B)$ in terms of $\cos \theta_A$, $\cos \theta_B$, $\sin \theta_A$, and $\sin \theta_B$.
- (IV) [10 pts.] With $\{\hat{x}, \hat{y}, \hat{z}\}$ the basis of a cartesian coordinate system, $\vec{A} = 3\hat{x} + 4\hat{y} - 4\hat{z}$. Find the unit vectors in the (x, y) plane that are perpendicular to \vec{A} .
- (V) [10 pts.] With $\{\hat{x}, \hat{y}, \hat{z}\}$ the basis of a cartesian coordinate system, $\vec{A} = \hat{x} + \hat{y} - \hat{z}$ and $\vec{B} = 2\hat{x} + \hat{y} - 3\hat{z}$. Find the two unit vectors perpendicular to both \vec{A} and \vec{B} .
- (VI) A two dimensional cartesian coordinate system has a unit vector basis $\{\hat{x}, \hat{y}\}$. The unit vectors \hat{x}' and \hat{y}' are the images of \hat{x} and \hat{y} by a rotation of angle θ .
- (a) [3 pts.] Express \hat{x}' and \hat{y}' in terms of \hat{x} , \hat{y} and θ .
 - (b) [3 pts.] By manipulating your answer to the previous question, obtain the expressions of \hat{x} and \hat{y} in terms of \hat{x}' , \hat{y}' and θ .
 - (c) [4 pts.] A vector $\vec{A} = A_x\hat{x} + A_y\hat{y}$ is given. Express the x' and y' components of \vec{A} .
- (VII) [10 pts.] We have $\{\hat{x}, \hat{y}, \hat{z}\}$ the basis of a cartesian coordinate system and we are considering a vector \vec{A} that makes an angle $\frac{\pi}{2} - \theta$ with \hat{z} (so θ really is the angle \vec{A} makes with the (x, y) plane) and whose perpendicular projection \vec{A}_P on the (xy) plane makes an angle ϕ with \hat{x} . Express the components of \vec{A} in the $\{\hat{x}, \hat{y}, \hat{z}\}$ basis in terms of the angles θ and ϕ , and A , the magnitude of \vec{A} .

- (VIII) [10 pts.] Consider the Earth as a perfect sphere of radius R . A point on the surface of the Earth is specified by its longitude l_1 and latitude h_1 . Another point is specified by l_2 and h_2 . Find the expression of the distance between the two points along the geodesic connecting them. On a sphere, geodesics between two points are sections of great circles formed by the intersection between the plane containing the center and the two points and the considered sphere.
- (IX) [10 pts.] A wheel of radius R rolls in a straight line along the x axis without slipping. Its center moves with a constant velocity V . The z axis measures vertical distance from the ground. A given point P of the wheel touches the road ($z = 0$) in $x = 0$ at time $t = 0$. Find the position \vec{r} , velocity \vec{v} and acceleration \vec{a} of point P as a function of time.
- (X) A cylinder of radius R_2 rolls without slipping on the inside surface of a cylinder of radius R_1 . The smaller cylinder moves in a counterclockwise direction and rolls around inside the other in a time period T . At time $t = 0$ the point P of the smaller cylinder is in contact with the larger cylinder on the x -axis as on the figure. (This might make you think of the spirograph of you childhood.)



A cylinder of radius R_2 rolling without slipping on the inside of another of radius R_1 goes all the way around in a time T

- (a) [4 pts.] Find the vector position $\vec{r}(t)$ of point P with respect to the point O at the center of the larger cylinder.
- (b) [3 pts.] Find the velocity $\vec{v}(t)$ of point P .
- (c) [3 pts.] Find the acceleration $\vec{a}(t)$ of point P .